



The Actuator Control Unit System or ACU System is a modular propulsion control system designed to be adaptable for multiple configurations with simple selection of modular components.

The ACU system can be used to control the waterjet deflector(s), waterjet steering, as well as engine throttle and gearbox engagement.

The main unit in the system is the ACU itself. The ACU is a controller box which can be connected to 3 different actuators depending on its role within the overall system.

The ACU can accept a analogue voltage signal (typically 0-5v), a CAN signal, or a mechanical input from morse cable via the built in potentiometer.

The ACU can be configured via the integrated button and 'traffic light' LED's.



Supply voltage

Idle current Motor current

**Current limit** Overheat limit PWM frequency Position control signal

Fault output

**EMC** 

Operating ambient temp Protection class

**Dimensions** 

12 Vdc ±20 % or 24 Vdc ±20 %, reverse polarity protected

typ. 50mA

max. 26 A (at 65°C ambient temp. and 25 % duty cycle) 26 A at 12 V, 13 A at 24 V

90°C 3,8 kHz

 $0 \dots 5 V$  or potentiometer  $5 k\Omega \dots$ 

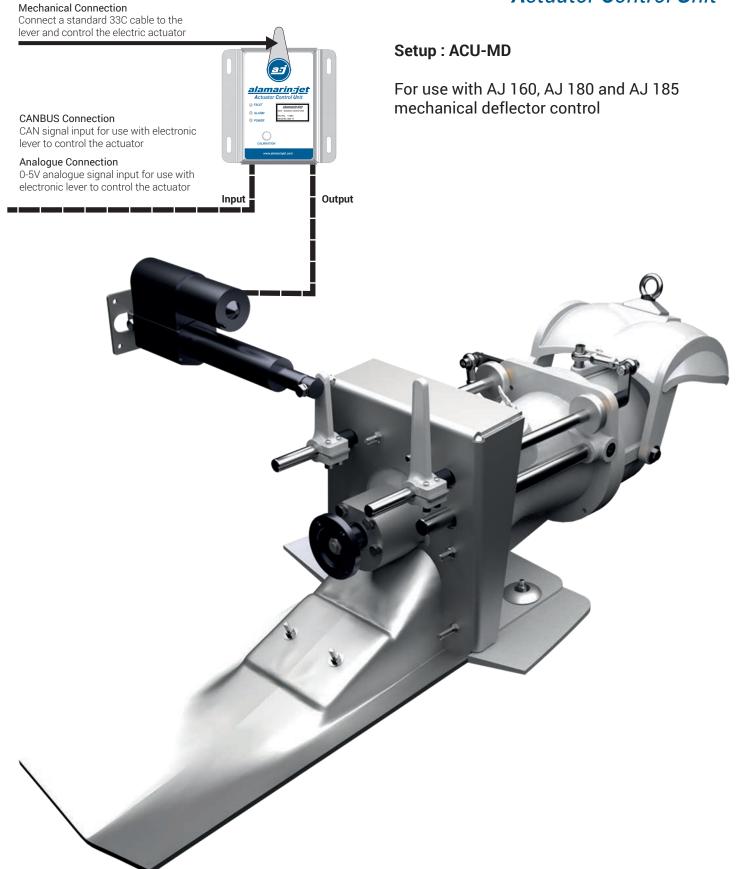
10 kΩ (scale can be calibrated) NPN open collector,

max 30V / 200mA CE-tested for marine environment

-40...65 °C IP67

155x150x35 mm



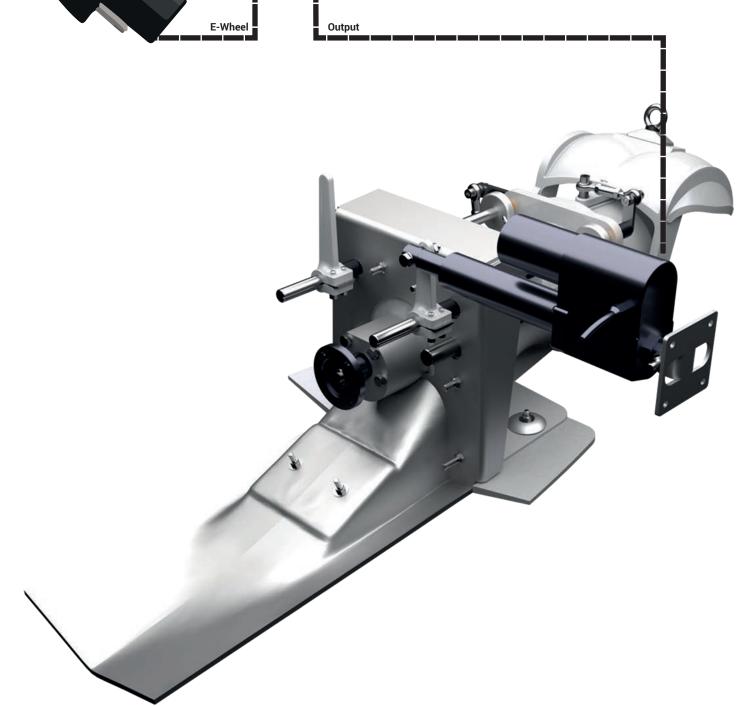






**Setup: ACU-ES** 

For use with AJ 160, AJ 180 and AJ 185 mechanical steering control





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